

**B.Tech. Degree VI Semester Examination in Marine Engineering**  
**May 2019**

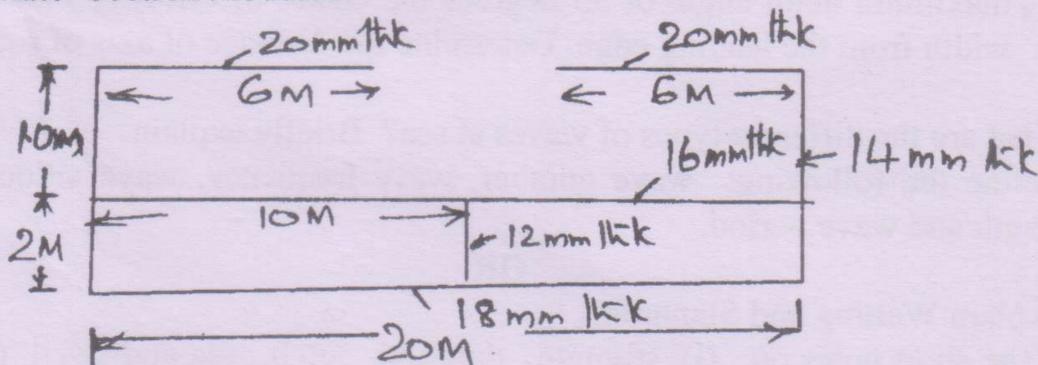
**MRE 1607 NAVAL ARCHITECTURE II**  
(2013 Scheme)

Time : 3 Hours

Maximum Marks : 100

(5 × 20 = 100)

- I. (a) Mid-ship section of a ship is given below: (17)  
Calculate Section modulus



- (b) If the maximum bending moment acting on the above section is 890 MNm, calculate the stresses acting on bottom shell, Tank top and at Deck. (3)

OR

- II. (a) The hull of a 80 m long rectangular barge has a uniformly, distributed mass of 640 t over the length. Machinery weight 200 t is at amidship for a length of 20 m. End tanks at aft and forward of 20 m length each are loaded 340 t each. Construct the curves of load, SF, and BM. (14)
- (b) Find: (i) location and values of maximum SF and BM. (6)  
(ii) Value of SF and BM at 25 m from aft.

- III. (a) Define P.C and Q.P.C. Derive it in terms of efficiencies. (3)
- (b) Following are the details obtained during acceptance trials of a ship: (17)  
Ship speed = 15.4 knots, Delivered power to propeller = 2500 kW, Effective power 1730 kW, Propeller Thrust = 274 KN, Propeller speed = 1.75 rps, Propeller efficiency = 64%, Pitch ratio = 0.75 Apparent slip = 5%. Calculate (i) Thrust deduction factor (ii) Taylor's wake fraction (iii) Propeller diameter.

OR

- IV. (a) Draw the profile of a propeller and mark the following dimensions/parts: (4)  
Diameter, Root dia, Rake, Tip, Face, Back.
- (b) A propeller of 6 m diameter have pitch ratio = 0.9, B.A.R = 0.48, rpm = 110, real slip ratio = 0.25, wake fraction = 0.3, propeller thrust = 700 KN and propeller efficiency = 0.65. Calculate: (i) Blade area (ii) Average pressure on the blade surface (iii) Ship speed (iv) Thrust power (v) Delivered power (vi) Torque on the shaft. (16)

- V. (a) Derive the angle of heel when the ship is taking a turning circle. (8)
- (b) Force parallel to ship's centre line is given by  $F = 577 A v^2$  newtons. (12)  
A = rudder area in sq.m, v = ship speed in m/sec. Rudder size is 5.5. m deep and 3.5 width with it's axis of rotation 0.4 m from leading edge. At an angle of rudder at 35 degrees the centre of effort is 32% of rudder width from leading edge.  
Maximum shear stress of rudder stock material is 70 MN/sq.m Calculate the following: (i) Minimum dia of rudder stock (ii) Speed to be restricted if the diameter is reduced by 20 mm due to corrosion.

OR

(P.T.O.)

- VI. (a) What are the different types of rudders? Explain with sketches. (4)  
 (b) The force acting normal to the plane of rudder is given by the expression:  
 $F_n = 20.17 A v^2 \times \alpha$  Newtons.  
 $A$  = rudder area  $v$  = speed of ship in m/sec.  $\alpha$  = rudder angle in degrees.  
 A manoeuvrability specification for a ship that requires a transverse rudder force ( $F_t$ ) of 75 KN is generated when angle of helm is 35 degrees when ship is travelling at a speed of 5 knots.  
 (i) Determine suitable dimensions of a rudder having depth to width ratio of 1.6. (6)  
 (ii) The rudder stock is designed to have a diameter = 320 mms with the allowable shear stress = 70 MN/sq.m at its service speed of 15 knots. At maximum helm angle of 35 degrees the centre of effort is 34% of rudder width from the leading edge. Determine the distance of axis of rotation. (10)
- VII. (a) What are the different types of waves at sea? Briefly explain. (10)  
 (b) Define the following: wave number, wave frequency, wave velocity, wave length and wave period. (10)
- OR**
- VIII. (a) Explain Wetting and Slamming. (5)  
 (b) Write short notes on: (i) strength, duration, fetch, sea and swell (ii) Wave spectrum (iii) Anti-rolling tanks. (15)
- IX. (a) Explain 2-node vertical mode & 3-node horizontal mode hull vibration on ships with suitable sketches. (10)  
 (b) What are the causes/consequences of vibration on ships? Describe. (10)
- OR**
- X. (a) Define the following w.r.t. Vibration: mode, node, anti-node, frequency and amplitude. (10)  
 (b) Define the term 'Resonance' and explain its significance w.r.t ship's propulsion system. (4)  
 (c) Describe how the hull vibration can be minimized in a vessel (i) in the design stage (ii) on the vessel already built. (6)

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